



Power In: Power input (8.4V/2S lipo battery)

STR IN: Steering servo signal input

STR OUT: Steering servo signal output

Gear IN: Landing gear signal input(Will need a Y signal wire to connect the receiver and retract controller and Gyro gear signal)

Brake IN:Brake wheel signal input

Brake out: Connect to the brake wheels

STR NOR/REV: Steering servo Forward/Reverse switchover(The steering servo works in opposite way, push this button to adjust it into the correct direction)

GEAR NOR/REV: Landing gear Forward/Reverse switchover(The landing gear opened but not the Gyro function not working,Push this button to correct the Gyro function. When the landing gear closed the Gyro will turn off.)

Gyro ST: Gyro Gain setting(-100% ~ +100%) If the jet not running straight line, adjust the rotary switch to “-” or “+” direction.